

MARTY BUILD GUIDE

Thank you for adopting a Marty! This guide will help you put your Marty together.

Make sure to:

- Do the steps in order.
- Pay attention to the part orientation.
- Be gentle with the motors.
- Not over-twist the servo horns.
- Not trap or squish the cables.
- Get help from an adult if your under 14.
- Have fun!

Top Tip: Go to *robotical.io/getstarted* for detailed written instructions.

















HAVE YOU GOT ALL YOUR ASSEMBLIES?

Check that you have assembled all 6 parts of Marty. You should have:



If in doubt, go to *robotical.io/getstarted* for detailed written instructions and support.

CHECK YOUR LEG ASSEMBLY

Check that you have assembled both of Marty's legs correctly and they resemble the image below.









Attach the head and servo stickers: attach the numbered stickers to the black servo connectors and clip the two head parts together.



Top Tip: the knee/hip servo cables (white & black) will be different lengths if gently pulled straight, the shorter cable is the Knee cable.







Attach the Battery, ON/OFF Cable and Power Cable: read the Saftey Warnings on the back of your Parts Guide.



Check the image below - make sure you have all the cables connected and in the correct place.



Optional - Tidy Marty's cables: using the cable ties provided in your Marty kit, strap the cables down to the base of Marty's head.





Personalise your Marty!



NEXT STEPS!

You have now finished building your Marty! To get your Marty up and running go to:

robotical.io/setupmarty



PLAY MARTY FOOTBALL



CONNECT A RASPBERRY PI - OPTIONAL

Raspberry Pi is not included in a standard Marty Kit



Connect a Raspberry Pi with the cable provided in your Marty pack.

PROGRAMMING MARTY

Use and interact with Marty on multiple platforms, with several different programming languages. Go to *robotical.io/getstarted* for support on the following:

- Scratch	The simplest way to begin programming your Marty. Combine blocks to build a program to get your Marty up and about.
₽ python™	Python is a more advanced programming language you can use to control Marty and <u></u> develop more complex programs.
JS JavaScript	You can use Javascript on a webpage to communicate with Marty over a websocket using the JavaScript API.
RaspberryPi	With a Raspberry Pi you can expand your Marty's functionality through the addition of advanced sensors and tools.
HROS	ROS, the Robot Operating System is an amazing set of advanced robotics tools used by industry and academia.





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class L	aserNode(object):
	Laser range finder ROS node for Marty
	init(self):
	<pre>super(LaserNode, self)init()</pre>
	rospy.init_node('laser')
	self.frequency = 10
	<pre>self.rate = rospy.Rate(self.frequency)</pre>
	self bridge = (v8ridge()
	<pre>self.robot_name = rospy.get_param("/name")</pre>
	<pre>self.framerate = rospy.get_param(</pre>
	<pre>self.robot_name + */raspicam/framerate*, 98)</pre>
	<pre>self.height = rospy.get_param(self.robot_name + "/raspicam/height", 480)</pre>
	<pre>self.width = rospy.get_param(self.robot_name + "/raspicam/width", 640)</pre>
	<pre>self.lower_threshold = rospy.get_param("/lower_threshold", [43, 70, 6])</pre>
	<pre>self.upper_threshold = rospy.get_param("/upper_threshold", [82, 255, 255])</pre>
	<pre>self.kernel_val = rospy.get_paran("/kernel_val", 0)</pre>
	<pre>self.video_out_param = rospy.get_param("/laser_video_out", False)</pre>
	<pre>setf.taser_type = rospy.get_param("/taser_type", "dot")</pre>
	<pre>set1.sample_rate = rospy.get_param("/sample_rate", 2)</pre>
	self cavera sub = rosov Subscriber/
	"/marty/camera/image/compressed", sensor msgs.msg.CompressedImage, self.im
	self.mask.pub = rospy.Publisher('/marty/laser/compressed', sepsor_msgs.psg.Com
	self.laser dist pub = rospy.Publisher(
	<pre>//marty/laser dist', std msgs.msg.Float32, gueue size=10)</pre>
	<pre>self.laser state pub = rospy.Publisher('/marty/opios', marty msgs.msg.GPIOs, r</pre>
	<pre>self.laser_scan_pub_ = rospy.Publisher('/marty/laser_scan', sensor_msgs.msg.La:</pre>
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robotical.io/gettingstarted

robotical.io/support

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